



Form: Course Syllabus	Form Number	EXC-01-02-02A
	Issue Number and Date	2/3/24/2022/2963 05/12/2022
	Number and Date of Revision or ModificaAon	15/10/2023
	Deans Council Approval Decision Number	265/2024/24/3/2
	The Date of the Deans Council Approval Decision	2024/1/23
	Number of Pages	06

1.	Course Title	Classical mechanics 2
2.	Course Number	0332352
3.	Credit Hours (Theory, Practical)	3
	Contact Hours (Theory, Practical)	3
4.	Prerequisites/ Corequisites	
5.	Program Title	B.Sc. Degree in Physics
6.	Program Code	
7.	School/ Center	School of science
8.	Department	Physics department
9.	Course Level	Third year
10.	Year of Study and Semester (s)	Second semester 2024-2025
11.	Program Degree	Bachelor
12.	Other Department(s) Involved in Teaching the Course	-



13.	Learning Language	English
14.	Learning Types	<input checked="" type="checkbox"/> Face to face learning <input type="checkbox"/> Blended <input type="checkbox"/> Fully online
15.	Online Platforms(s)	<input type="checkbox"/> Moodle <input checked="" type="checkbox"/> Microsoft Teams
16.	Issuing Date	1 Feb 2025
17.	Revision Date	10 Feb 2025

18. Course Coordinator:

Name: Dr Ala'a Azzam Contact hours: Contact hours: Mon 10:00-11:00, Sun 12:30 - 13:30

Office number: 303

Phone number: 22023

Email: alaa.azzam@ju.edu.jo

19. Other Instructors:

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20. Course Description:

Lagrangian mechanics; Hamiltonian mechanics; dynamics of systems of particles; dynamics of rigid bodies; coupled oscillators.

21. Program Intended Learning Outcomes: (To be used in designing the matrix linking the intended learning outcomes of the course with the intended learning outcomes of the program)

PILO's	*NaAonal QualificaAons Framework Descriptors*
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	Competency (C)	Skills (B)	Knowledge (A)
1. Identify, formulate, and solve broadly-defined technical or scientific problems by applying knowledge of Mathematics and Science and/or technical topics to areas relevant to the discipline	<input type="checkbox"/>	X	<input type="checkbox"/>
2. Formulate or design a system, process, procedure or program to meet desired needs	<input type="checkbox"/>	X	<input type="checkbox"/>
3. Develop and conduct experiments or test hypotheses, analyze and interpret data and use scientific judgment to draw conclusions	<input type="checkbox"/>	X	<input type="checkbox"/>
4. Communicate effectively with a range of audiences in oral or written forms and exhibit ethical and professional values.	X	<input type="checkbox"/>	<input type="checkbox"/>
5. Reflect the impact of technical and/or scientific solutions in economic, environmental, and societal contexts.	X	<input type="checkbox"/>	<input type="checkbox"/>



6. Function effectively on teams that establish goals, plan tasks, meet deadlines, and analyze risk and uncertainty.	X	<input type="checkbox"/>	<input type="checkbox"/>
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* Choose only one descriptor for each learning outcome of the program, whether knowledge, skill, or competency.

22. Course Intended Learning Outcomes: (Upon completion of the course, the student will be able to achieve the following intended learning outcomes)

Course ILOs #	The learning levels to be achieved						Competencies
	Remember	Understand	Apply	Analyse	Evaluate	Create	
1. Explain the principles of Lagrangian and Hamiltonian formulations of classical mechanics		X					Not directly a competency — this is primarily knowledgebased.



2. Apply Lagrange's equations to derive the equations of motion for mechanical systems with constraints.			X				Not directly a competency — this is a technical skill outcome.
3. Analyze the dynamics of systems of particles and rigid bodies using generalized coordinates.				X			Not directly a competency — technical/ analytical skill.



4. Formulate and solve problems involving Hamiltonian mechanics, including canonical transformations and conservation laws.				X			Indirectly related to scientific judgment and decisionmaking (PO4, PO11 — problemsolving under uncertainty)
5. Model and interpret physical systems such as coupled oscillators and small oscillations using normal modes.				X			Indirectly supports lifelong learning and complex problemsolving by developing modeling capability.



6. Evaluate the physical significance of conserved quantities (energy, momentum, angular momentum) in the context of symmetries.					X		Competency: Scientific judgment, ethical implications of conservation principles (PO8, PO7).
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23. The matrix linking the intended learning outcomes of the course -CLO's with the intended learning outcomes of the program -PILOs:

PILO's * CLO's	1	2	3	4	5	Descriptors**		
						A	B	C
1	X					X		
2	X	X					X	
3	X						X	
4	X		X				X	X
5		X	X				X	
6			X		X			X

***Linking each course learning outcome (CLO) to only one program outcome (PLO) as specified in the course matrix.**

****Descriptors are determined according to the program learning outcome (PLO) that was chosen and according to what was specified in the program learning outcomes matrix in clause (21).**

24. Topic Outline and Schedule:

Week	Lecture	Topic	ILO/s Linked to Topic	Learning Types	Platform Used	Synchronous / Asynchronous	Evaluation Methods	Learning Resources
1	1	Introduction to Lagrangian Mechanics	SO1, SO2	FF	Teams	Synchronous	Quiz, Problem Set	Marion & Thornton Chap. 1, Lecture slides



1	2	Principle of Least Action & Variational Principles	SO1, SO2, SO3	FF	Teams	Synchronou s	Homework	Marion & Thornton Chap. 2
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1	3	Derivation of Lagrange's Equations	SO1, SO2, SO3	FF	Teams	Synchronou s	Problem Solving	Marion & Thornton Chap. 3
2	4	Applications of Lagrangian Mechanics	SO2, SO3	FF	Teams	Blended	Homework, Quiz	Marion & Thornton Chap. 4
2	5	Hamiltonian Mechanics: Introduction	SO1, SO4	FF	Teams	Blended	Group Discussion	Marion & Thornton Chap. 5
2	6	Canonical Equations and Transformations	SO1, SO4	FF	Teams	Blended	Homework	Marion & Thornton Chap. 6
3	7	Conservation Laws and Symmetries	SO4, SO5	FF	Teams	Synchronou s	Quiz	Marion & Thornton Chap. 7
3	8	Dynamics of Systems of Particles: Overview	SO1, SO2	FF	Teams	Synchronou s	Problem Solving	Marion & Thornton Chap. 8
3	9	Generalized Coordinates and Constraints	SO1, SO2	FF	Teams	Synchronou s	Homework	Marion & Thornton Chap. 9
4	10	Equations of Motion for Particle Systems	SO1, SO2	FF	Teams	Synchronou s	Problem Set	Marion & Thornton Chap. 10
4	11	Dynamics of Rigid Bodies: Rotational Motion	SO1, SO3	FF	Teams	Synchronou s	Quiz	Marion & Thornton Chap. 11
4	12	Euler's Equations of Motion	SO1, SO3	FF	Teams	Synchronou s	Problem Solving	Marion & Thornton Chap. 12



5	13	Motion of a Symmetric Top	SO1, SO3	FF	Teams	Synchronou s	Homework	Marion & Thornton Chap. 13
5	14	Coupled Oscillators: Introduction	SO1, SO2	FF	Teams	Blended	Homework, Quiz	Marion & Thornton Chap. 14
5	15	Normal Modes of Oscillation	SO1, SO3	FF	Teams	Blended	Group Project	Marion & Thornton Chap. 14

6	16	Energy Transfer in Coupled Oscillators	SO1, SO3	FF	Teams	Blended	Problem Set	Marion & Thornton Chap. 14
6	17	Small Oscillations and Stability Analysis	SO1, SO3	FF	Teams	Synchronou s	Quiz	Marion & Thornton Chap. 15
6	18	Phase Space and Hamiltonian Dynamics	SO1, SO4	FF	Teams	Synchronou s	Homework	Marion & Thornton Chap. 16
7	19	Poisson Brackets and Canonical Transformations	SO1, SO4	FF	Teams	Synchronou s	Problem Solving	Marion & Thornton Chap. 16
7	20	Hamilton-Jacobi Theory	SO1, SO4	FF	Teams	Synchronou s	Quiz	Marion & Thornton Chap. 17
7	21	Action-Angle Variables	SO1, SO4	FF	Teams	Synchronou s	Homework	Marion & Thornton Chap. 17
8	22	Central Force Motion and Effective Potential	SO1, SO2	FF	Teams	Synchronou s	Problem Solving	Marion & Thornton Chap. 18
8	23	Two-body Problem	SO1, SO2	FF	Teams	Synchronou s	Quiz	Marion & Thornton Chap. 18



8	24	Perturbation Methods	SO1, SO3	FF	Teams	Blended	Homework	Marion & Thornton Chap. 19
9	25	Variational Principles for Continuous Systems	SO1, SO2	FF	Teams	Synchronou s	Problem Set	Marion & Thornton Chap. 20
9	26	Rigid Body Kinematics	SO1, SO3	FF	Teams	Synchronou s	Quiz	Marion & Thornton Chap. 21
9	27	Inertia Tensor and Principal Axes	SO1, SO3	FF	Teams	Synchronou s	Homework	Marion & Thornton Chap. 21
10	28	Gyroscopic Motion	SO1, SO3	FF	Teams	Synchronou s	Problem Solving	Marion & Thornton Chap. 22

10	29	Stability of Motion in Rigid Bodies	SO1, SO3	FF	Teams	Synchronou s	Quiz	Marion & Thornton Chap. 23
10	30	Advanced Coupled Oscillator Systems	SO1, SO3	FF	Teams	Blended	Group Project	Marion & Thornton Chap. 24
11	31	Nonlinear Oscillations	SO1, SO3	FF	Teams	Blended	Homework	Marion & Thornton Chap. 25
11	32	Dissipative Systems	SO1, SO3	FF	Teams	Blended	Quiz	Marion & Thornton Chap. 25
11	33	Resonance Phenomena	SO1, SO3	FF	Teams	Blended	Problem Set	Marion & Thornton Chap. 26
12	34	Application of Lagrangian to Electromagnetic Systems	SO1, SO3	FF	Teams	Synchronou s	Homework	Marion & Thornton Chap. 27



12	35	Hamiltonian Chaos Introduction	SO1, SO4	FF	Teams	Synchronou s	Quiz	Marion & Thornton Chap. 28
12	36	Symplectic Integrators	SO1, SO4	FF	Teams	Synchronou s	Problem Solving	Marion & Thornton Chap. 28
13	37	Numerical Methods in Classical Mechanics	SO1, SO4	FF	Teams	Blended	Homework	Marion & Thornton Chap. 29
13	38	Project Work Introduction and Guidelines	SO2, SO6	FF	Teams	Synchronou s	Project Proposal	Custom material
13	39	Student Presentations and Discussions 1	SO4, SO6	FF	Teams	Synchronou s	Presentation	Studentprepared materials
14	40	Student Presentations and Discussions 2	SO4, SO6	FF	Teams	Synchronou s	Presentation	Studentprepared materials

14	41	Review of Lagrangian Mechanics	SO1, SO2, SO3	FF	Teams	Synchronou s	Quiz	Marion & Thornton Chap. 1-4
14	42	Review of Hamiltonian Mechanics	SO1, SO4	FF	Teams	Synchronou s	Quiz	Marion & Thornton Chap. 5-7
15	43	Review of Rigid Body Dynamics	SO1, SO3	FF	Teams	Synchronou s	Problem Solving	Marion & Thornton Chap. 11-13
15	44	Review of Coupled Oscillators	SO1, SO3	FF	Teams	Synchronou s	Problem Solving	Marion & Thornton Chap. 14-16
15	45	Comprehensive Problem Solving Session	SO1SO6	FF	Teams	Synchronou s	Comprehen sive Exam Prep	Full course material
16	46	Final Exam Preparation	SO1SO6	FF	Teams	Synchronou s	Exam Review	Full course material



25. Evaluation Methods:

Opportunities to demonstrate achievement of the ILOs are provided through the following assessment methods and requirements:

Evaluation Activity	Mark wt. (%)	CILO 1	CILO 2	CILO 3	CILO 4	CILO 5	CILO 6
First Exam	20%	X	X	X			
Second Exam – If any	15%	X	X	X			
Final Exam	30%	X	X	X	X	X	
Class Work	35%	X	X	X	X		X
Total	100%						

* According to the instructions for granting a Bachelor's degree.

**According to the principles of organizing semester work, tests, examinations, and grades for the bachelor's degree.

Mid-term exam specifications table*

No. of quesAons/ cogniAve level						No. of quesAons per CLO	Total exam mark	Total no. of quesAons	CILO/ Weight	CILO no.
Create 10%	Evaluate 10%	analyse 10%	Apply 20%	Understand 20%	Remember 30%					
	1	3	3	2	3	1	25	3	1/7.5	3

Final exam specifications table

No. of quesAons/ cogniAve level						No. of quesAons per CLO	Total exam mark	Total no. of quesAons	CILO Weight	CILO no.
Create 10%	Evaluate 10%	analyse 10%	Apply 20%	Understand 20%	Remember 30%					
1	3	3	3	3	3	3	50	13	0.23	1
	1	1	1	1	1	1	50	13	0.07	2



	1	1	1	1	1	1	50	13	0.07	3
	2	2	2	2	2	2	50	13	0.15	4
	4	4	4	4	4	4	50	13	0.3	5
	3	3	3	3	3	3	50	13	0.23	6

26. Course Requirements:

(e.g.: students should have a computer, internet connection, webcam, account on a specific software/platform...etc.):

27. Course Policies:



A- Attendance policies:

- Students are expected to attend all scheduled lectures, tutorials, and laboratory sessions.
- Attendance will be recorded regularly.
- A minimum of **75% attendance** is required to be eligible for final examination, in line with university regulations.
- Repeated absences without valid justification may lead to **withdrawal from the course**.

B- Absences from exams and submitting assignments on time:

- Absence from **midterm or final exams** without prior approval or acceptable justification (e.g., certified illness, family emergency) will result in a grade of zero for the missed exam.
- Late submission of assignments will incur a **penalty of 10% per day**, up to 3 days. Beyond that, submissions may not be accepted unless a valid excuse is provided.

C- Health and safety procedures:

D- Honesty policy regarding cheating, plagiarism, misbehavior:

- Academic honesty is strictly enforced. Any form of **cheating, plagiarism, or academic misconduct** will be reported and penalized in accordance with university regulations.
- Penalties may include a **grade of zero**, course failure, or **disciplinary action**.
- Misbehavior during class or exams (including unauthorized device use) is also subject to disciplinary action.

E- Grading policy:

- **Midterm Exam:** 25%
- **Class Participation & Assignments:** 25%
- **Final Exam:** 50%

F- Available university services that support achievement in the course:

- **Library Services:** Access to course textbooks, reference materials, and academic databases.

28. References:



A- Required book(s), assigned reading and audio-visuals:

Main Textbook:

- *Classical Dynamics of Particles and Systems* by Jerry B. Marion and Stephen T. Thornton, 5th Edition.
 - This book covers Lagrangian and Hamiltonian mechanics, rigid body dynamics, and coupled oscillations — all core topics in this course.

B- Recommended books, materials, and media:

Recommended Books:

- *Introduction to Classical Mechanics* by David Morin — excellent for problem-solving practice.
- *Mechanics* by L.D. Landau and E.M. Lifshitz — more advanced theoretical treatment.
- *Analytical Mechanics* by Fowles & Cassiday — another widely used reference.

Online Resources:

- MIT OpenCourseWare Physics – Classical Mechanics (8.01)
- Khan Academy Physics – [Classical Mechanics Topics](#) **Simulation Tools & Software**

(Optional):

- PhET Interactive Simulations: <https://phet.colorado.edu/>
- Tracker Video Analysis (for motion and system modeling)

29. Additional information:

Name of the Instructor or the Course Coordinator: Signature:

Date:

.....Dr Ala'a Azzam.....

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The University of Jordan

Name of the Head of Quality Assurance
CommiRee/ Department

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Signature:

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Date:

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Name of the Head of Department

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Signature:

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Date:

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Name of the Head of Quality Assurance
CommiRee/ School or Center

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Signature:

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Date:

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Name of the Dean or the Director

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Signature:

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Date:

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